CHARACTERISTICS OF THE AIRS VERSION 5 RETRIEVAL ALGORITHM

Joel Susskind
GSFC Sounder Research Team
AIRS Science Team Meeting

September 26, 2006

OVERVIEW OF AIRS/AMSU RETRIEVAL METHODOLOGY

Physically based system

Independent of GCM except for surface pressure

Uses cloud cleared radiances \hat{R}_i to produce solution

 \hat{R}_i represents what AIRS would have seen in the absence of clouds

Basic steps

Initial cloud clearing produces \hat{R}_i^0 AIRS regression guess parameters based on cloud cleared radiances \hat{R}_i^0 Update cloud clearing using AIRS regression guess parameters: produces \hat{R}_i Sequentially determine surface parameters, T(p), q(p), $O_3(p)$, CO(p), $CH_4(p)$, using \hat{R}_i

Generate error estimates and apply quality control

Determine cloud parameters consistent with retrieved state and observed radiances

SIGNIFICANT IMPROVEMENTS IN AIRS VERSION 5.0 ALGORITHM

Physical retrieval algorithm

Improved radiative transfer parameterization accounts for Non Local Thermodynamic Equilibrium (non-LTE) effects

Allows for use of many more shortwave temperature sounding channels

Most longwave temperature profile channels used only for cloud clearing

Shortwave temperature sounding channels used for temperature profile

Error estimates

New methodology developed to provide accurate case by case error estimates

Uses residuals of the physical retrieval and cloud clearing steps

Error estimates used directly for quality control

AIRS only cloud clearing/retrieval system Version 5.0 AO

Developed as a backup system in case AMSU A fails

CHANNELS AND FUNCTIONS USED IN V5.0

Temperature sounding channels

664 cm⁻¹ - 713 cm⁻¹

2198 cm⁻¹ - 2395 cm⁻¹

shortwave tropospheric temperature sounding channels only

Surface retrieval channels

2421 cm⁻¹ - 2659 cm⁻¹

shortwave window channels only

Emissivity functions

1 SW ϵ function, LW emissivity remains at ϵ_v^{reg}

1 ρ function

Cloud clearing

655 cm⁻¹ - 812 cm⁻¹

longwave cloud clearing channels only

RATIONALE FOR VERSION 5 CHANNEL SET

- Theory says cloud clearing (determination of η) should be performed using only LW channels and T(p), T_s determined from SW channels
 Errors in T(p), T_s are less affected by errors in Tⁿ(p), Tⁿ_s used to determine ηⁿ
- T_s , ϵ_v now determined only from channels near 2390 cm⁻¹ used for lower tropospheric T(p)Scene surface non-homogeneity results in ν dependent effective values of T_s , ϵ_v Surface non-homogeneity in actual T_s , ϵ_v will result in less degradation in T(p)

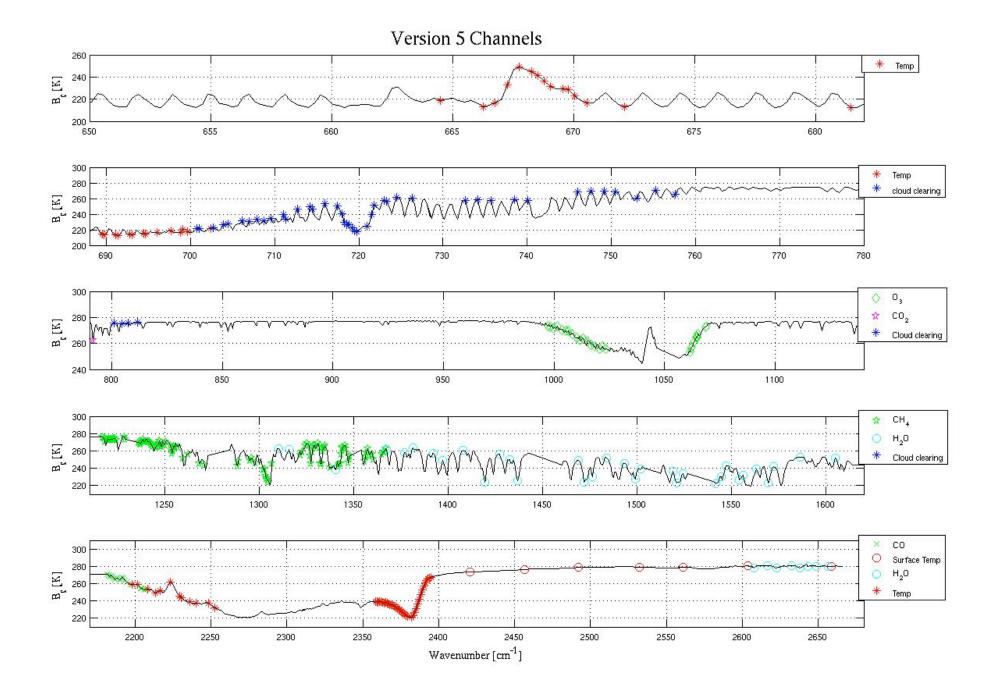
Plans for further improvement - Version 6

Determine T_s , ε_{sw} , T(p) in a single step (no prior surface retrieval step)

Do surface parameter retrieval with LW window channels to determine ε_{LW}

(3 functions?)

Will help subsequent cloud clearing, q(p), $O_3(p)$ retrievals



GENERATION OF EMPIRICAL ERROR ESTIMATES δX_i

This step is done after physical retrieval is otherwise completed

Methodology used for δSST , $\delta T(p)$ is identical

Uses 16 internally computed values of convergence tests Y_i

Thresholds of 12 Y_i terms are used in Version 4 quality control

 δX_i , error estimate for X_i is computed according to

$$\delta X_i = \sum M_{ij} Y_j$$

Determination of M_{ij}

Use profiles with "truth"

$$\Delta X_i = \left| X_i - X_i^{TRUTH} \right|$$

Each profile now has $\Delta X_i, Y_j$

 M_{ij} found which minimizes RMS $|\delta X_i - \Delta X_i|$

 M_{ij} generated using all September 29, 2004 cases in which IR retrieval is accepted ECMWF taken as "truth" to provide ΔX_i

M_{ij} tested on January 25, 2004

Same basic approach is used for $\delta \hat{R}_i, \delta q(p)$

METHODOLOGY USED FOR QUALITY CONTROL

Temperature Profile T(p)

Define a profile dependent pressure, p_g above which the temperature profile is flagged as good

Use error estimate $\delta T(p)$ to determine p_g

Start from 70 mb and set p_g to be the pressure at the first level below which

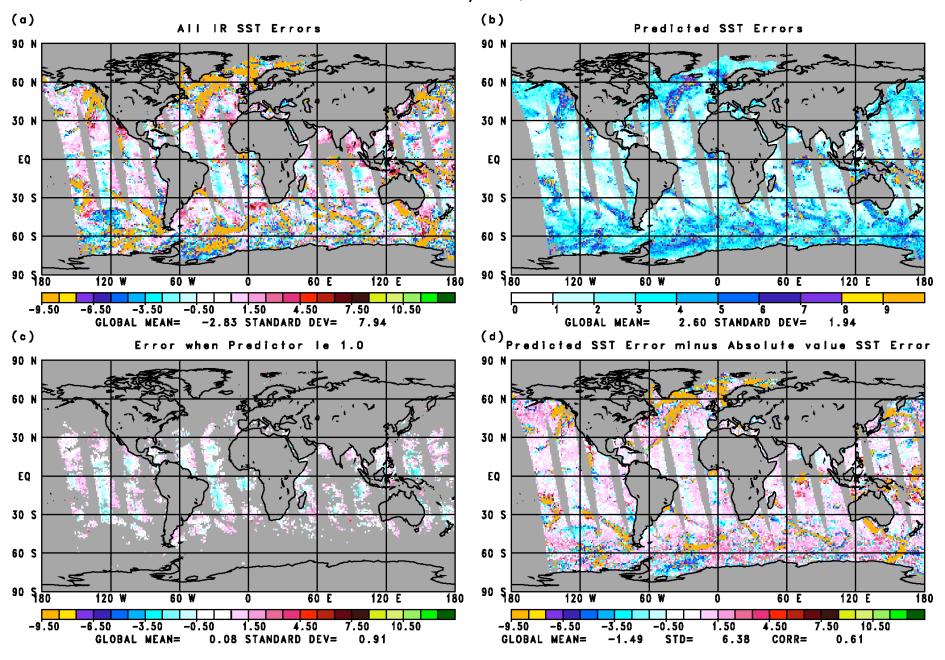
 $\delta T(p)$ > threshold for n (currently = 3) consecutive layers

Temperature profile statistics include errors of T(p) down to $p = p_g$

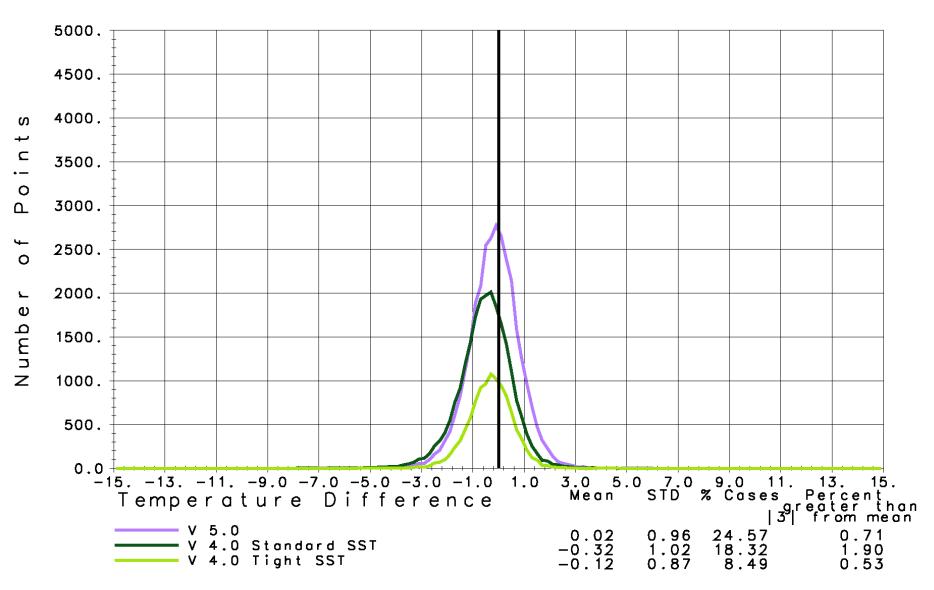
Sea surface temperature SST

Flag SST as good if δ SST < threshold

Surface Skin Temperature (K) Retrieved minus ECMWF January 25, 2003

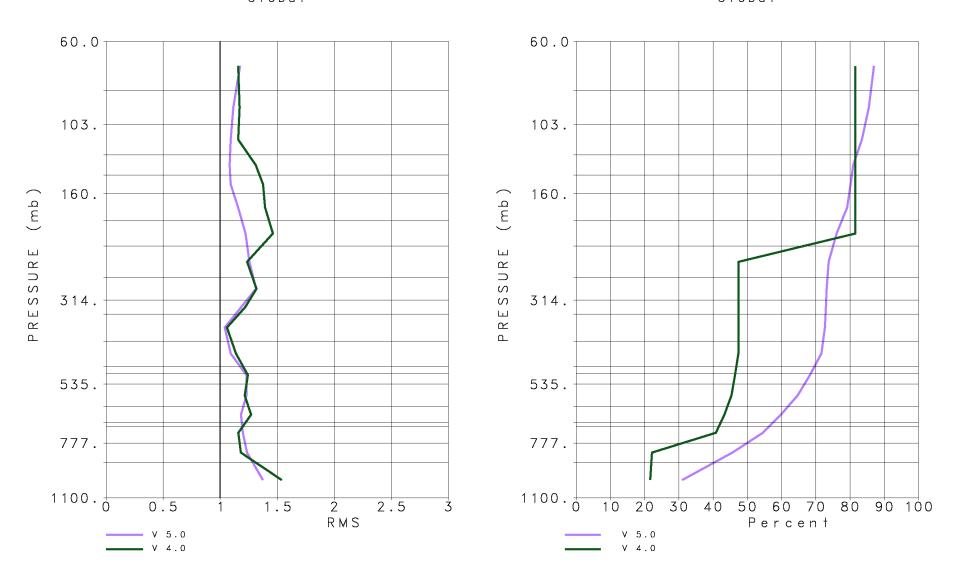


Surface Skin Temperature Difference
January 25, 2003 Daytime and Nighttime combined
50 N to 50 S Non-Frozen Ocean

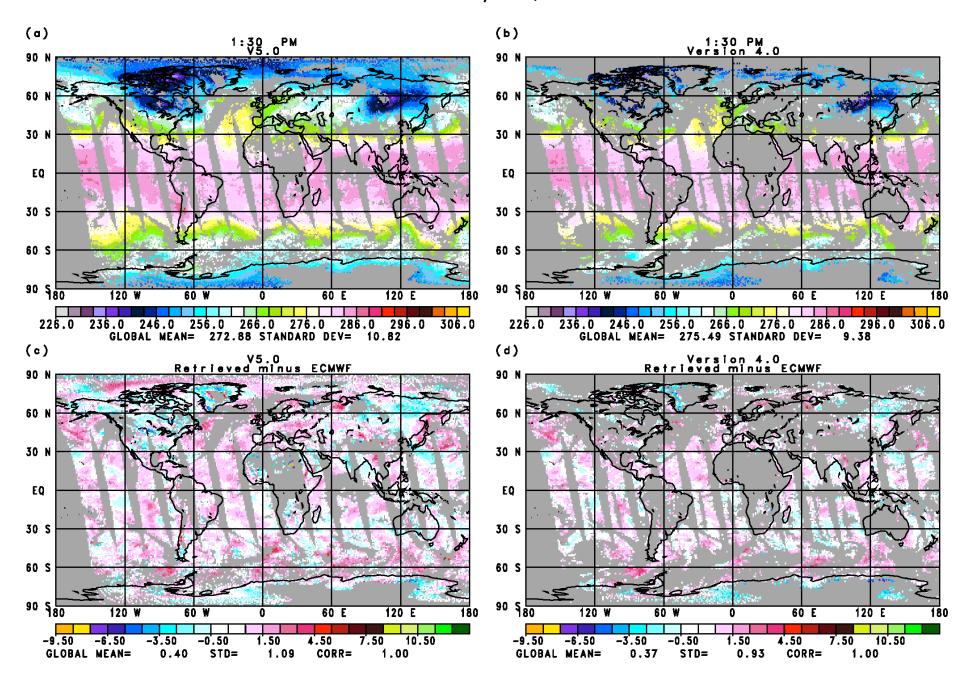


LAYER MEAN RMS TEMPERATURE (°C) GLOBAL DIFFERENCES FROM "TRUTH" January 25, 2003 Global

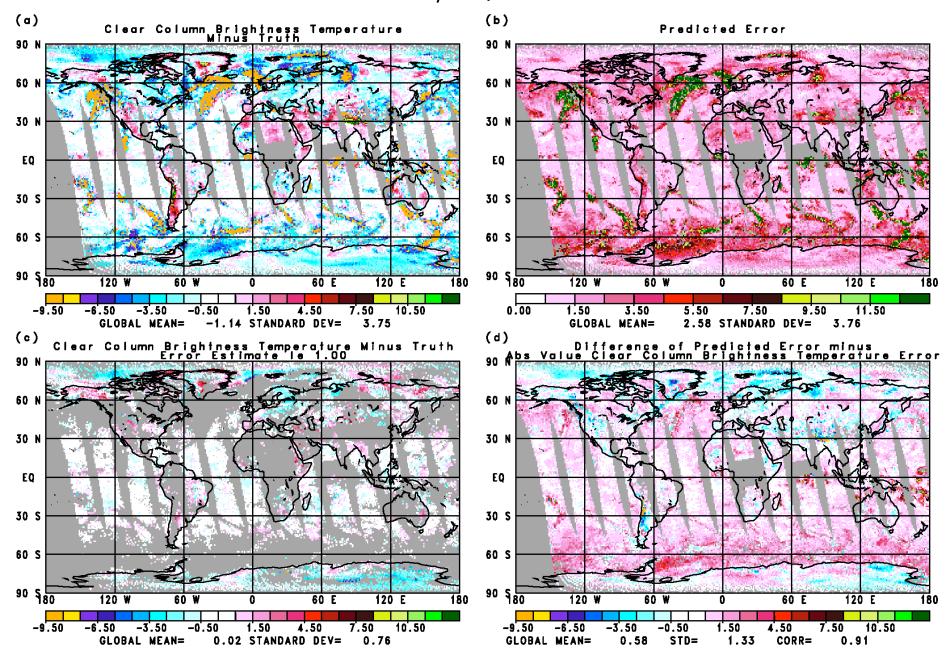
Percent of IR/MW Cases Included January 25, 2003 Global



700 mb TEMPERATURE (K) January 25, 2003



Clear Column Brightness Temperature (K)
724.52 cm | Channel
January 25, 2003 v5.0



Clear Column Brightness Temperature minus "Truth" January 25, 2003 Global 650 to 756 cm⁻¹ a 260 Mean Clear 250 Column Brightness 240 Temperature 230 220 b 2.5 STD (°K) 2.0 1.5 1.0 0.5 650 670 680 690 730 740 750 660 700 710 Wavenumber, cm version 5.0 EE less than 1.00 version 4.0 Mid-Trop Good Noise

AIRS ONLY RETRIEVAL SYSTEM (AO)

Retrieval Steps

- 1 Cloudy regression produces X^1 (AMSU retrieval produces X^1 in AIRS/AMSU system
- 2 \hat{R}_i^1 computed using X^1
- 3 Generate X^{reg} using \hat{R}_i^1 , $X^{reg} = X^2$
- 4 \hat{R}_i^2 computed using X^2
- 5 Physical retrieval gives X^3 Uses \hat{R}_i^2 , starts with X^2
- 6 \hat{R}_i^3 computed using X^3
- Physical retrieval uses \hat{R}_i^3 , gives solution X^4 Steps 2-7 are almost identical to AIRS/AMSU retrieval system AMSU channels 1, 2, and 15 are not used in AO water vapor retrieval
- Apply quality control
 Analogous to QC in AIRS/AMSU retrieval system but does not use 3 AMSU based tests
 13 terms instead of 16 terms

OVERVIEW OF AIRS CLOUD CLEARING PROCEDURE

Uses radiances in 9 fields of view R_{ij} channel i, FOV j within AMSU A FOR

Allows for up to 8 cloud formations

 \overline{R}_i = average radiance over 9 FOV's

$$\hat{R}_i^n = \overline{R}_i + \sum_{j=1}^9 \eta_j^n \left(R_{i,j} - \overline{R}_i \right) = \overline{R}_j + \sum_{j=1}^9 \eta_j^n \Delta R_{i,j}$$

9 values of η_i determine \hat{R}_i for all channels

We compute expected values of $R_{i,CLR}^n$ from a state X^n to obtain η^n

$$\eta_{j}^{n} = \left(\Delta R' N^{-1} \Delta R\right)^{-1} \Delta R' N^{-1} \Delta R_{CLR}^{n}$$

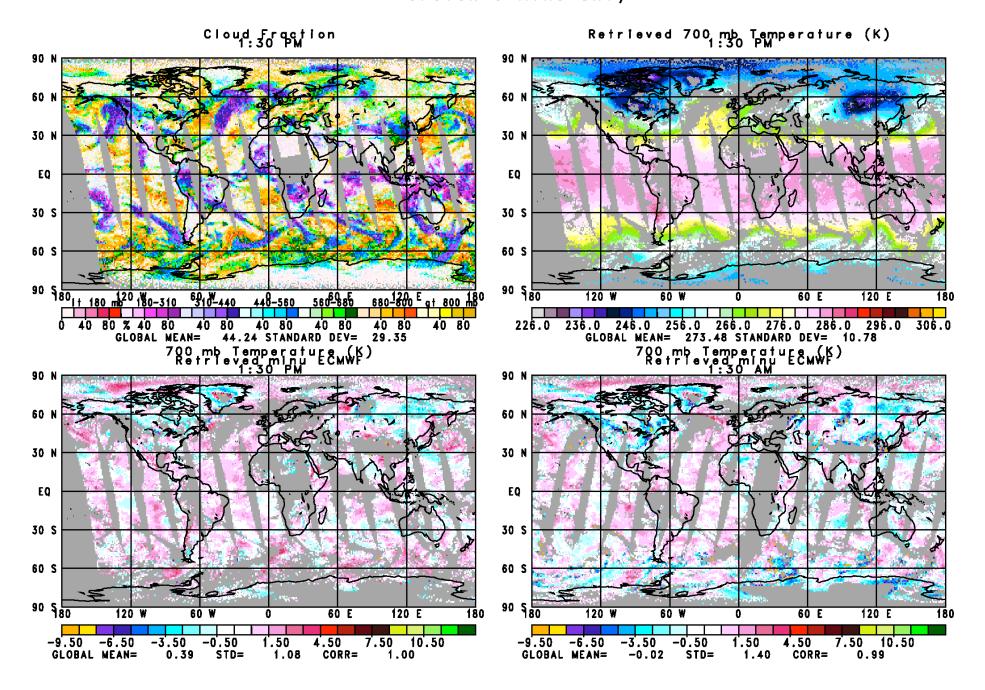
 $\Delta R_{CLR,i}^n = R_{i,CLR}^n - \overline{R}$ $R_{i,CLR}^n$ computed from surface and atmospheric state X^n

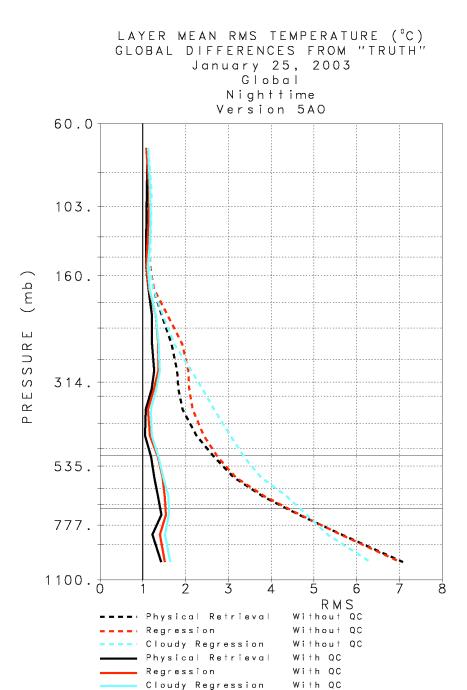
N =channel noise covariance

R_{i,CLR} should in principle be an unbiased state

Larger biases may result when X¹ comes from cloudy regression than AMSU retrieval

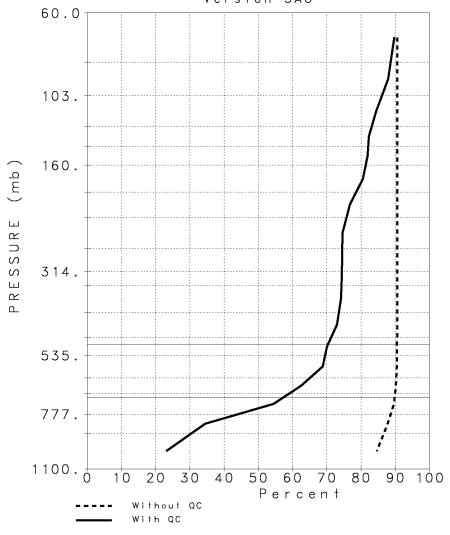
January 25, 2003 Version 5 AIRS Only

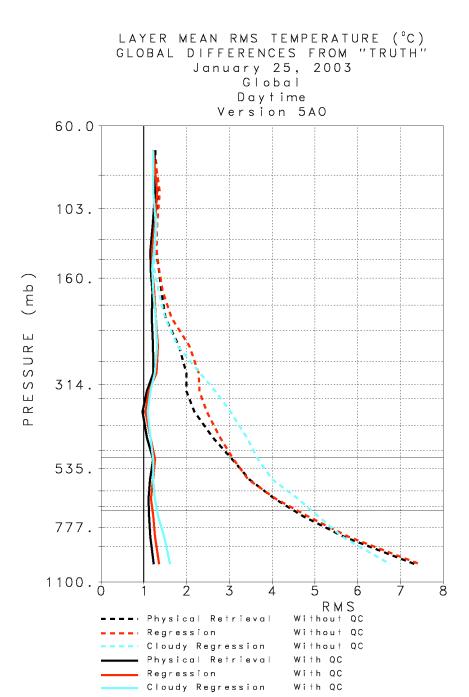




Percent of IR Retrieval Cases Included

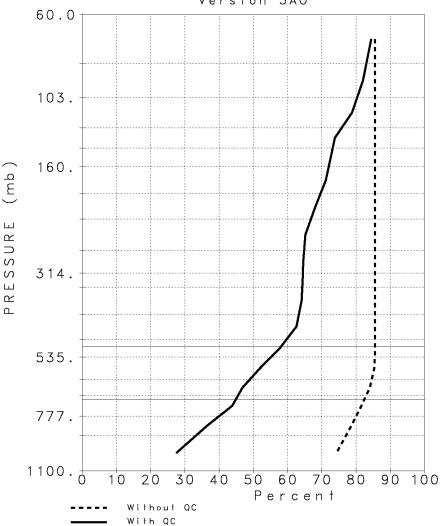
January 25, 2003 Global Nighttime Version 5AO



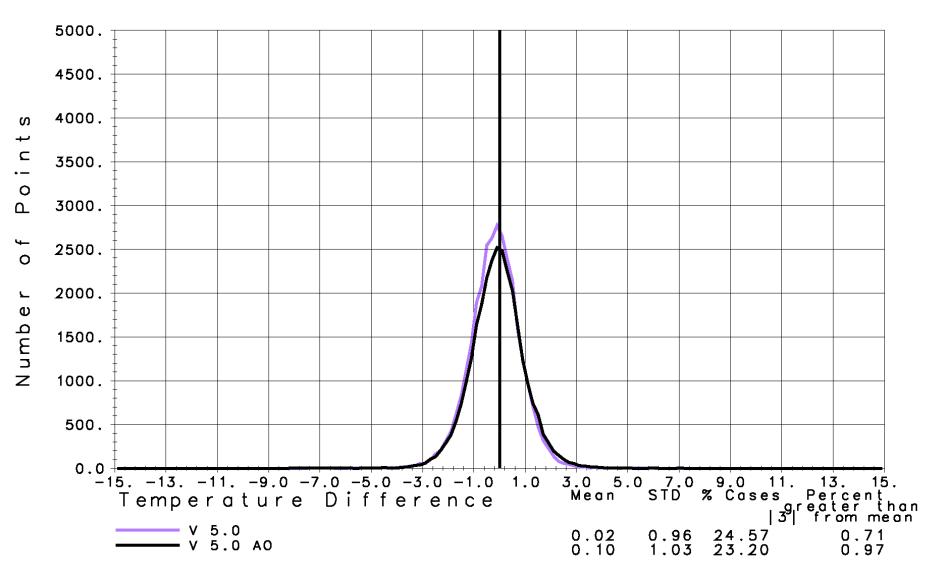


Percent of IR Retrieval Cases Included



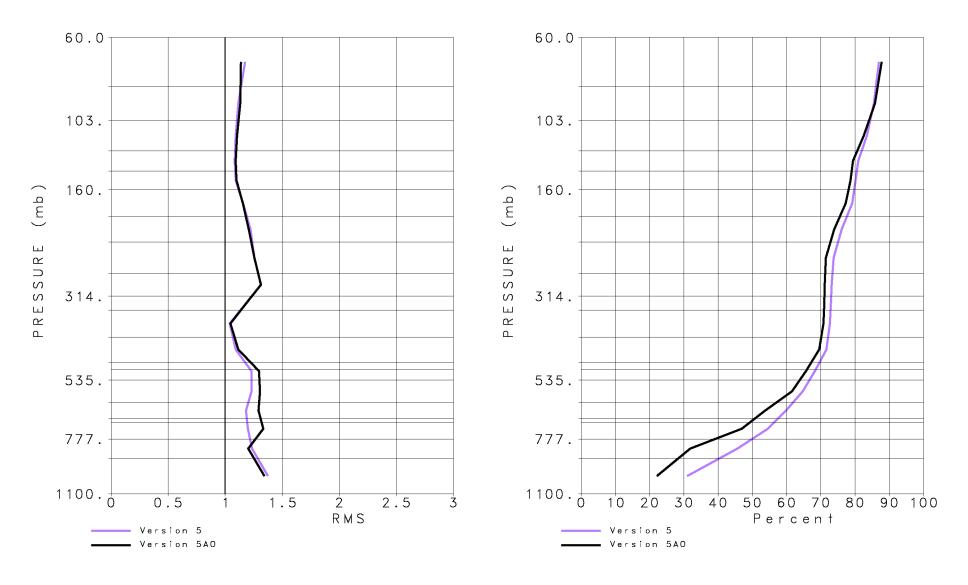


Surface Skin Temperature Difference
January 25, 2003 Daytime and Nighttime combined
50 N to 50 S Non-Frozen Ocean



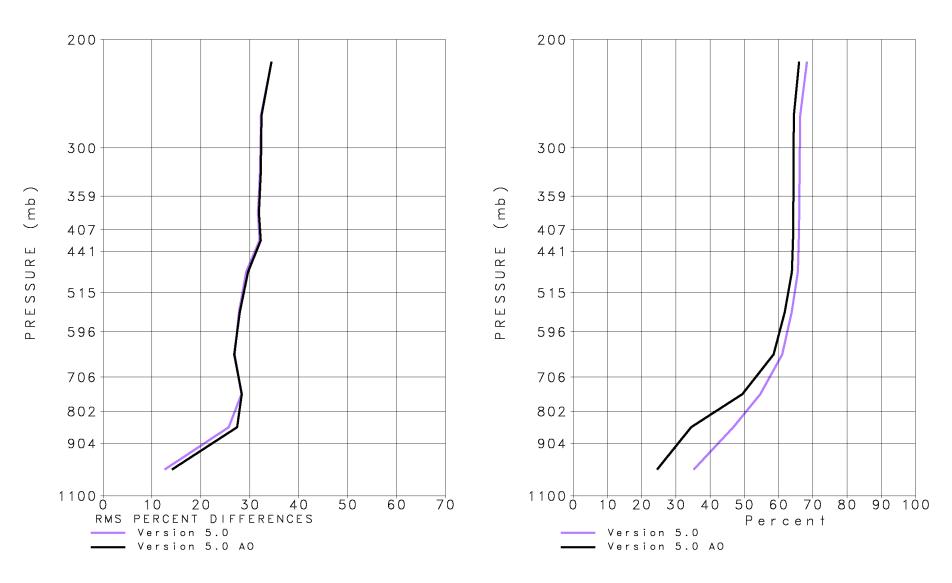
LAYER MEAN RMS TEMPERATURE (°C) GLOBAL DIFFERENCES FROM "TRUTH" January 25, 2003 Global

Percent Yield Temperature January 25, 2003 Global



1 Km LAYER PRECIPITABLE WATER % DIFFERENCES FROM "TRUTH" January 25, 2003 Global

Percent Yield Water January 25, 2003 Global



SUMMARY

Quality controlled Version 5.0 retrievals are significantly better than Version 4.0

Accuracy and spatial coverage

Uses primarily shortwave channels for temperature and surface retrievals

Case by case error estimates are very accurate

Used directly for quality control

Enhance utility of products for both weather and climate applications

Allows for use of AIRS only cloud clearing system

AIRS only backup system performs very well

Demonstrates importance of spectral channels between 2350 cm⁻¹ and 2400 cm⁻¹ with low noise